# PARKER J KNOPF | parker.knopf@gmail.com

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# CAREER OBJECTIVE

Dedicated to leveraging proven experience with academic success to advance company goals. An unparalleled innate self-driven tenacity to problem-solve, lead, and collaborate with others to further technological innovation!

# **EDUCATION**

MECHANICAL ENGINEERING, MS   (Controls and Mechatronics)	2023 - 2024
MECHANICAL ENGINEERING, BS   GPA: 3.87 (Cum-laude)	2019 - 2023

## JNIVERSITY OF CALIFORNIA. SAN DIEGO

- Relevant Courses: Signals and Systems, System ID, Control, Statics and Dynamics, Mathematical Computation, Programing, Thermodynamics, Material Science, Fluid Dynamics, Solid Mechanics
- Clubs: Triton Robotics (Engineer Lead), Human Powered Submarine (Engineer), Club Water Polo (President)

# EXPERIENCE

### HOLOGIC | R&D (Mechanical and Systems) Engineer - Intern

### **Precision Instrument System Engineering Project**

- Developed from scratch a precision ultrasonic embedded system instrument to characterize tube height, relieving the duty of a engineers to conduct root-cause analysis of an instrument defect
- Trusted with autonomy to select electronic components, develop mechanical design, and program software

### **Prototype Development of Next Generation Product**

- Integrated electronic modules into a self designed and assembled functional first-generation prototype
- Showcased to marketing team and other stakeholders, receiving positive feedback on prototype •
- Conducted multidisciplinary tasks including software development, hardware integration, and iterative product development based on gathered feedback from external workflow operations

### MORIMOTO LAB | Mechanical Engineer - Researcher

### **UCSD Soft Robotics Research Lab**

- Prototyped and developed an innovative non-invasive endovascular surgical device in collaboration with a small team of student researchers under the guidance of Professor Tania Morimoto.
- Evaluated feasibility through clinical trials, lab experimentation, literature research, and FEA •
- Participated in clinical collaborator meetings to aid in product development and clinical adoption •

## VALITUS TECHNOLOGIES | Mechanical Engineer - Intern

## **Product Development for Start-up Corporation**

- Contributed to design of Critical AI Security Project for the USAF (United States Air Force)
- Designed final CAD geometry in preparation for mass production injection molding •
- Quickly adapted to company workflow, including the use of foreign files created by international partners •

# RELEVANT ENGINEERING PROJECTS

## WEARABLE HAPTIC ARM | Obstacle Avoidance During Teleoperation (paper)

- Project Scope: Novel haptic armband to mimic obstacle collision of a RR manipulator during teleop.
- Designed mechanical actuators and implemented serial-protocol for cross-system communication

## **REVERSE OSMOSIS TESTING RIG | Senior Project from OceanWell (portfolio link)**

- Project Scope: Structural rig and electronics board with actuators/sensors to characterize fluid flow •
- Lead weekly scrum meetings with a student engineer team overseen by career engineers/scientists

# SKILLS

Solidworks (CSWP)	Serial Interface	MATLAB	Autocad	Leadership	National Champion in SkillsUSA
4-axis Milling	Python/Java/C++	Ros2	CAM	Commutative	Auto-Manufacturing Tech. Comp.
3D-Printing	Embedded Systems	OpenCV	Linux	Organization	1st Place UCSD Robotic Comp.

# December 2022 - September 2023

June 2022 - September 2022

500+ hours

# 300+ hours

# April 2019 - September 2020

100+ hours

Fall 2023 | 60+ hours

Spring 2023 | 200+ hours

# **AWARDS**